

# More about Momentum

Physics 1425 Lecture 15

# Elastic One-Dimensional Collisions 1

- An elastic collision is one in which mechanical energy is conserved.
- **First example:** two **equal masses** with opposite velocities:



- Conservation of *momentum* tells us they bounce back with equal speeds, and conservation of *energy* ensures each ball just has its velocity reversed.

- After:



## Clicker Question

Suppose we have two **equal masses**, one initially at **rest**, the other approaching from the left at velocity  $v$ . What is the velocity of the *center of mass*?



- A. 0
- B.  $0.5v$
- C.  $v$
- D. Something else

# Clicker Question

What is the velocity of the center of mass **after** the elastic collision?



- A. 0
- B.  $0.5v$
- C.  $-0.5v$
- D. Something else

## Clicker Question

What would be the velocity of the center of mass after a completely inelastic collision? (Assume the balls stick together.)



- A. 0
- B.  $0.5v$
- C.  $-0.5v$
- D. Something else

## Clicker Question

Suppose we have a 1 kg mass initially at rest, and a 2 kg mass approaching from the left at velocity  $v$ . What is the velocity of the center of mass?



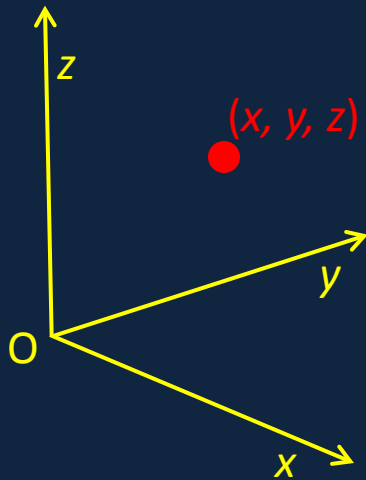
- A.  $0.2v$
- B.  $0.33v$
- C.  $0.5v$
- D.  $0.67v$
- E.  $v$

# Looking at Collisions...

- Collisions of two objects, in one or two dimensions, are often easier to understand (as you'll see) if we examine the *motions relative to the center of mass*.
- This is called working in the center of mass frame of reference.
- If there are no external forces acting on the system, overall momentum is conserved, and **the center of mass moves at constant velocity** relative to any given inertial frame.

# Reminder: a Frame of Reference

Frame of reference:



*The frame can be envisioned as three meter sticks at right angles to each other, like the beginning of the frame of a structure.*

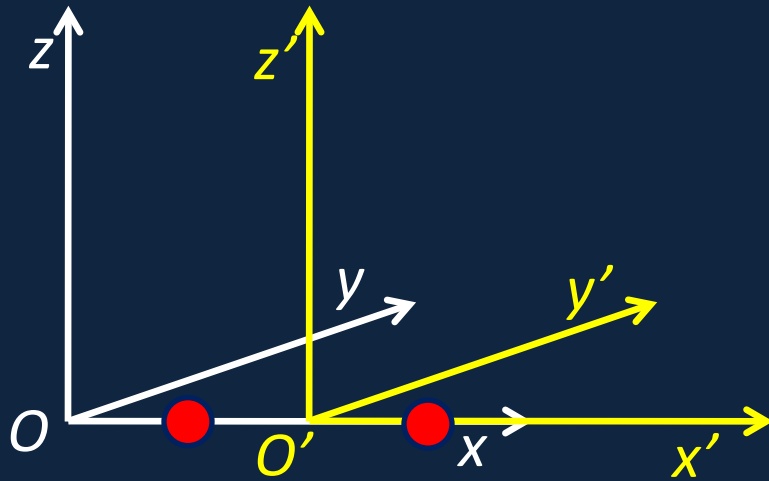
To measure **motion**, we must first measure **position**.

We measure position relative to some fixed point **O**, called the **origin**.

We give the **ball's** location as **(x, y, z)**: we reach it from **O** by moving **x** meters along the x-axis, followed by **y** parallel to the y-axis and finally **z** parallel to the z-axis.



# Two Inertial Frames of Reference



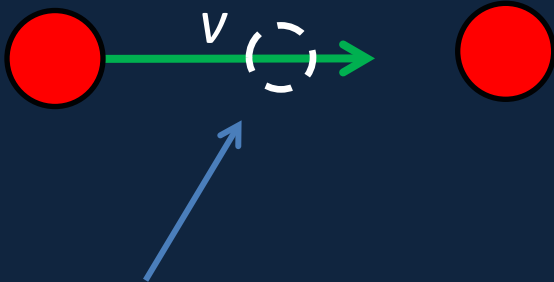
The fixed lab frame is in white. The CM frame is in yellow. The origin  $O'$  is always at the center of mass of the two balls. With no external forces,  $O'$  moves at constant velocity relative to  $O$ , so both frames are inertial, both conserve momentum.

- Suppose the first frame, call it the lab frame, is three sticks fixed on the bench.
- Our experiment is an elastic collision of **two balls**, no outside forces.
- The second frame, the CM frame, has its origin at the center of mass of the two balls. It's moving at a *constant velocity* relative to the lab frame.

# Equal Masses, Two Frames

- **Lab frame:**

- Before:



CM has velocity  $v/2$  in lab frame.

- After: just add the CM velocity of  $v/2$  to the velocities in the CM frame!

- **CM Frame:**

- Before:



- After:



# Elastic One-Dimensional Collisions

- Third example: two unequal masses in the CM frame:



- Total momentum  $\vec{P} = M\vec{v}_{CM}$  is always zero in the CM frame, so they have equal but opposite momenta. As they collide, the equal elastic forces reduce both momenta to zero at the same instant—then supply *exactly the same forces in reverse* as the balls spring back.
- Therefore, as they part, each ball has its initial velocity reversed.



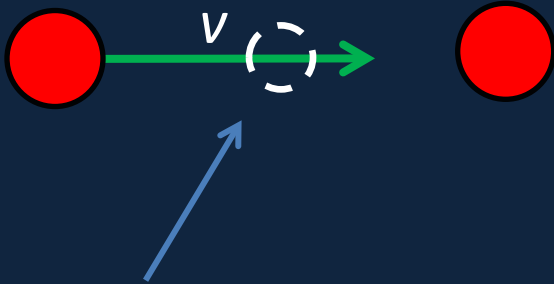
# Elastic One-Dimensional Collisions

- What about unequal masses **not** in the center of mass frame of reference?
- The simplest approach is to first find the velocity of the center of mass, then the velocities of the two particles relative to the center of mass, then realize that **after the collision, these relative velocities will have been reversed** as we just discussed.
- In other words, solve the problem in the center of mass frame, then translate back!

# Equal Masses, Two Frames, Inelastic

- **Lab frame:**

- Before:



CM has velocity  $v/2$  in lab frame.

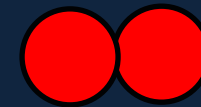
- After: just add the CM velocity of  $v/2$  to the velocities in the CM frame!

- **CM Frame:**

- Before:



- After: stuck!



## Clicker Question

For the one-dimensional inelastic collision of a mass  $m$  moving at velocity  $v$  hitting and sticking to an initially stationary mass  $m$ , is the kinetic energy loss:

- A. Greater in the center of mass frame?
- B. Greater in the lab frame (one mass initially at rest)?
- C. The same in both?

## Clicker Question

I drop a large ball with a small ball balanced on top of it from a height of one meter. The small ball stays on top during the fall. After the large ball bounces off the floor, **how high do you predict the small ball will go?**

- A. 1 meter
- B. 2 meters
- C. 3 meters
- D. 4 meters or more

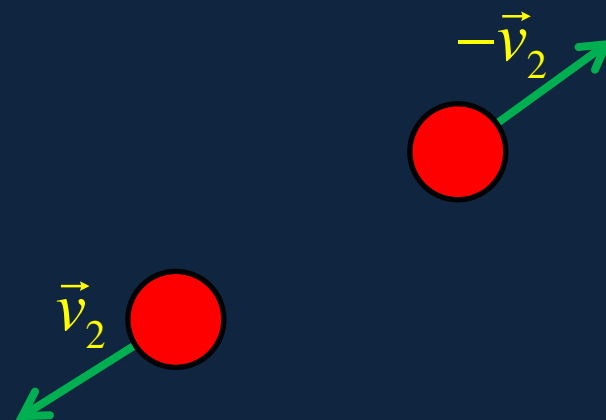
# Two-Dimensional CM Elastic Collisions

- As in one dimension, in the CM frame *the total momentum is zero throughout*—BUT now that is **not enough to solve the problem**.
- The balls could come out at a **different angle**, as any pool player knows.
- **Animation!**

- Before:



- After:

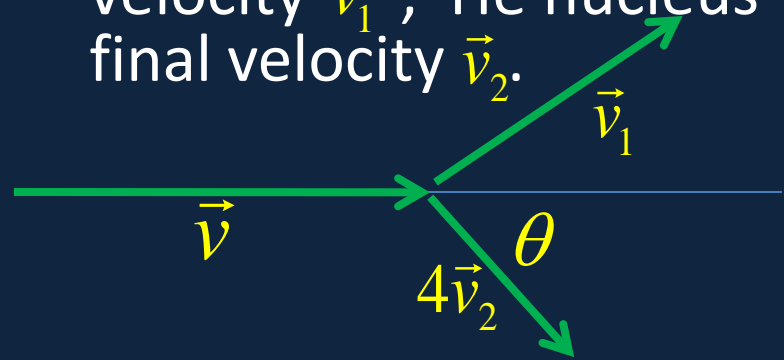




# Problem from Book

- A neutron collides elastically with a helium nucleus (at rest initially) whose mass is **four times that of the neutron**.
- The helium nucleus is **observed to move off at an angle  $\theta$** .
- Determine the angle of the neutron, and the speeds of the two particles, and after the collision. The neutron's initial velocity is  $\vec{v}$ .

- Take final neutron velocity  $\vec{v}_1$ , He nucleus final velocity  $\vec{v}_2$ .



- Conservation of momentum:

$$\vec{v} = \vec{v}_1 + 4\vec{v}_2$$

- Conservation of energy:

$$\vec{v}^2 = \vec{v}_1^2 + 4\vec{v}_2^2$$

- Go to next slide...

# Solving the problem...

- We have momentum conservation and energy conservation equations:

$$\vec{v} = \vec{v}_1 + 4\vec{v}_2 \qquad v^2 = v_1^2 + 4v_2^2$$

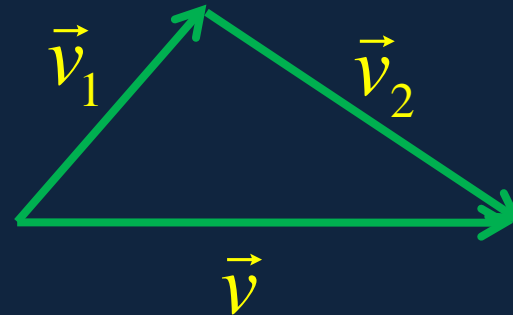
- **Important!** The **only** angle we know is that between  $\vec{v}$ ,  $\vec{v}_2$ .
- The strategy is to eliminate one variable by choosing one in the momentum equation to put in the energy equation.
- We choose  $\vec{v}_1$  because we can square  $(\vec{v} - 4\vec{v}_2)$ : we know the angle between these two vectors.
- This gives  $v^2 = (\vec{v} - 4\vec{v}_2)^2 + 4v_2^2 = v^2 - 8vv_2 \cos \theta + 20v_2^2$
- from which immediately  $v_2 = 0.4v \cos \theta$ .

# Another Book Problem...

- **61.** (III) Prove that in the elastic collision of two objects of identical mass, with one being a target initially at rest, the angle between their final velocity vectors is always  $90^\circ$ .

- All masses are equal—so momentum vectors are just velocity vectors multiplied by  $m$ , let's say  $m = 1$ .
- Initial velocities  $\vec{v}, 0$ .
- Final velocities  $\vec{v}_1, \vec{v}_2$ .

$$\vec{v} = \vec{v}_1 + \vec{v}_2, \quad v^2 = v_1^2 + v_2^2$$



- From Pythagoras' theorem, this triangle of the velocities is a *right angle* triangle!

Check this with the [animation](#)